

Ordering data

6SL3210-1KE21-7AF1



Client order no. : Order no. : Offer no. : Remarks :

Item no.: Consignment no.: Project :

Rated data Input		General tech. specifications			
		Power factor λ	0.70 0.85		
Number of phases	3 AC	Offset factor cos φ	0.9	95	
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.9	7	
Line frequency	47 63 Hz	Sound pressure level (1m)	63	dB	
Rated current (LO)	21.50 A	Power loss	0.2	24 kW	
Rated current (HO)	18.20 A	Ambient conditions			
Output		Cooling	Air coolin	a using an integrated fan	
Number of phases	3 AC	Cooling	Air cooling using an integrated fan		
Rated voltage	400 V	Cooling air requirement	0.009 m³	/s	
Rated power (LO)	7.50 kW	Installation altitude	1000 m		
Rated power (HO)	5.50 kW	Ambient temperature			
Rated current (IN)	18.20 A	Operation	-10 40	°C (14 104 °F)	
Rated current (LO)	16.50 A	Transport	-40 70	°C (-40 158 °F)	
Rated current (HO)	12.50 A	Storage	-40 70	°C (-40 158 °F)	
Max. output current	25.00 A	Relative humidity			
Pulse frequency	4 kHz			0 °C (104 °F), condensation	
Output frequency for vector control	0 240 Hz	Max. operation	and icing	and icing not permissible	
Output frequency for V/f control	0 650 Hz	Closed-loop control techniques			
In firmware V4.7 and higher, due to legal requirements, the maximum		V/f linear / square-law / parame	eterizable	Yes	
output frequency is restricted to 550 H		V/f with flux current control (Fo	CC)	Yes	

Overload capability

Low Overload (LO)

 $150\,\%$ base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

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V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

Communication					
Communication	PROFINET				

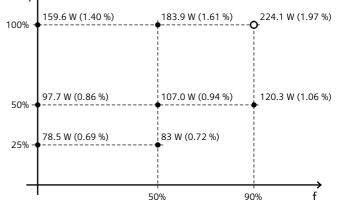


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Mechanical	Mechanical data		Connections	
Degree of protection	IP20 / UL open type	Signal cable		
Size	FSB	Conductor cross-section	0.15 1.50 mm² (28 16 AWG	
Net weight	2.30 kg	Line side		
Width	100.0 mm	Version	Plug-in screw-type terminals	
Height	196.0 mm	Conductor cross-section	4.00 6.00 mm² (12 10 AWG	
Depth	225.0 mm	Motor end		
Inputs/ outputs		Version	Plug-in screw terminals	
tandard digital inputs		Conductor cross-section	4.00 6.00 mm² (12 10 AWG	
Number	6	DC link (for braking resistor)		
Switching level: 0→1	11 V	Version	Plug-in screw terminals	
Switching level: 1→0	5 V	Conductor cross-section	4.00 6.00 mm² (12 10 AWG	
Max. inrush current	15 mA	PE connection	On housing with M4 screw	
ail-safe digital inputs		Max. motor cable length		
Number	1	Shielded	50 m	
igital outputs		Unshielded	100 m	
Number as relay changeover contact	1	Converter losses to EN 50598-2*		
Output (resistive load)	DC 30 V, 1 A	Efficiency class	IFO.	
Number as transistor	1	Comparison with the reference converter (90% / 100%) -66.38 %		
Output (resistive load)	DC 30 V, 1 A			
nalog/ digital inputs		I ↑		
Number	1 (Differential input)	159.6 W (1.40 %)	183.9 W (1.61 %)	



 $\label{thm:converter:thm:con$

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*calculated values; increased by 10% according to the standard

PTC/ KTY interface

Analog outputs

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

1 (Non-isolated output)

Standards

Compliance with standards UL, cUL, CE, C-Tick

CE marking EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

Technical data are subject to change! There may be discrepancies between calculated and rating plate values.